

**Amendments to the Specification:**

Please replace the paragraph beginning on page 1, line 6, with the following rewritten paragraph:

The invention concerns a hydraulic control system for a mobile equipment, such as a wheel loader or a backhoe loader, ~~in accordance with the preamble of claim 1.~~ loader.

Please replace the paragraph beginning on page 2, line 28, with the following rewritten paragraph:

This object is achieved through a hydraulic control system for a mobile equipment, in particular for a backhoe loader or a wheel loader, having ~~the features of claim 1.~~ a shovel retained on a boom which is adapted to be pivoted by means of a boom cylinder, which may be pivoted by means of a shovel cylinder adapted to be controlled by means of a shovel control unit, wherein the shovel position may be fed back via a transmitting member to an orientation control device whereby the shovel cylinder may be controlled, and wherein the orientation control device comprises an actuation head in operative connection with the transmitting member, the position change of said actuation head during a pivoting movement of the shovel being convertible via a control device into a control signal for keeping the shovel in a target angular position, characterized in that a basic position of the actuation head is variable, and in that the transmitting member is connected with the actuation head such that both downward pivoting of the shovel and upward pivoting of the shovel from its target angular position results in a positional change of the actuation head, so that depending on this positional change a control signal for returning the shovel into its target angular position at the shovel cylinder may be emitted, and also the actuation head may be reset in the direction of its pre-set basic position.

Please replace the paragraph beginning on page 5, line 9, with the following rewritten paragraph:

Manufacture of the orientation control device is particularly simple if the transmitting member has the form of a thrust rod which ~~attaeks~~engages in parallel with the boom at the shovel, wherein the end portion of the thrust rod removed from the shovel is mounted on a frame of the equipment through the intermediary of a movable bearing and is connected with the actuation lever via the afore-mentioned springs or the lever mechanism or means having a similar action.

Please replace the paragraph beginning on page 6, line 17, with the following rewritten paragraph:

The pivoting movement of the boom 2 is executed by means of a double-acting boom cylinder 12 which may be supplied with pressure medium via a cylinder control unit 14. The boom cylinder 12 is articulatedly supported at the frame 10 and ~~attaeks~~engages with its piston rod ~~at-on~~ the boom 2. The pivoting movement of the shovel 4 relative to the boom 2 is executed with the aid of a shovel cylinder-~~14~~ 16, the housing of which is linked to the boom 2, and the piston rod of which ~~attaeks-at~~engages with the shovel 4. This shovel cylinder-~~14~~ 16, too, is realized as a double-action cylinder and is supplied with pressure medium via a shovel control unit 18.

Please replace the paragraph beginning on page 6, line 30, with the following rewritten paragraph:

In accordance with Fig. 1, a thrust rod 20 is moreover mounted at the shovel-~~16~~ 4 by means of a thrust rod articulation 22, said thrust rod extending in the represented angular position in parallel with the boom 2. The end portion of the thrust rod 20 which is removed from the shovel 4 is supported on a frame-side movable bearing 24 adapted to move relative to the boom 2 in the event of a change of the angular position of the shovel 4. At a constant angular position of the shovel 4 relative to the equipment, the boom and the thrust rod 20 as well as the pivoted articulation 6 and the thrust rod bearing 22 on the one hand and the

linking mechanism 8 and the movable bearing 24 on the other hand form a parallelogram that changes its geometry during the pivoting movement of the boom 2, however essentially remains a parallelogram (as long as the angular position of the shovel 4 relative to the axles of the backhoe loader remains unchanged).

Please replace the paragraph beginning on page 7, line 14, with the following rewritten paragraph:

In the embodiment represented in Fig. 1, the thrust rod 20 which is supported at the movable bearing 24 is connected via a spring or spring assembly 26 with an actuation lever 28 of a hydraulic pilot control device 30. The control lever 28 is acted upon in a direction opposite to the spring assembly 26 by a tensile spring assembly 32 having its one end portion removed from the control lever 28 attached to an actuation means 34 which, in the represented embodiment, consists of an actuation lever 36 and a sliding joint 38 connected with the latter either directly or via signal lines, the position of which is variable, and which ~~attacks at~~ engages with the tensile spring assembly 32.